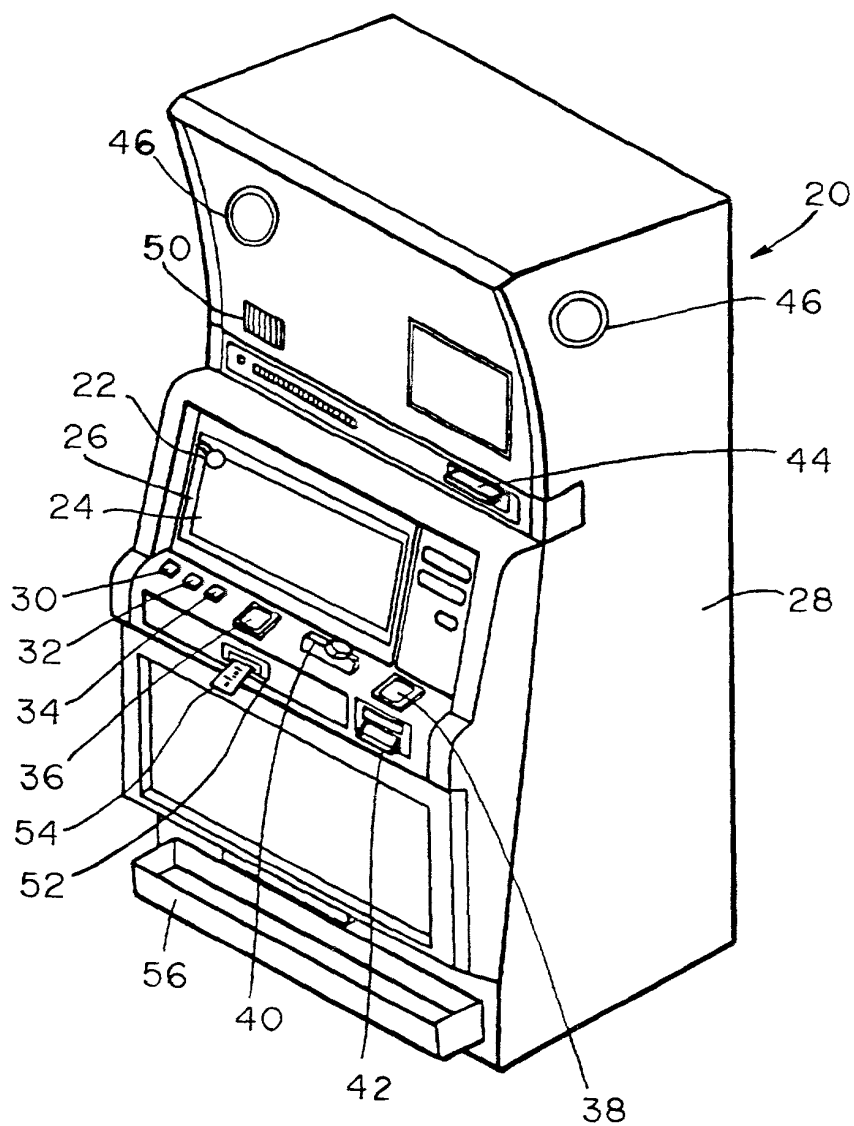


FIG. 1



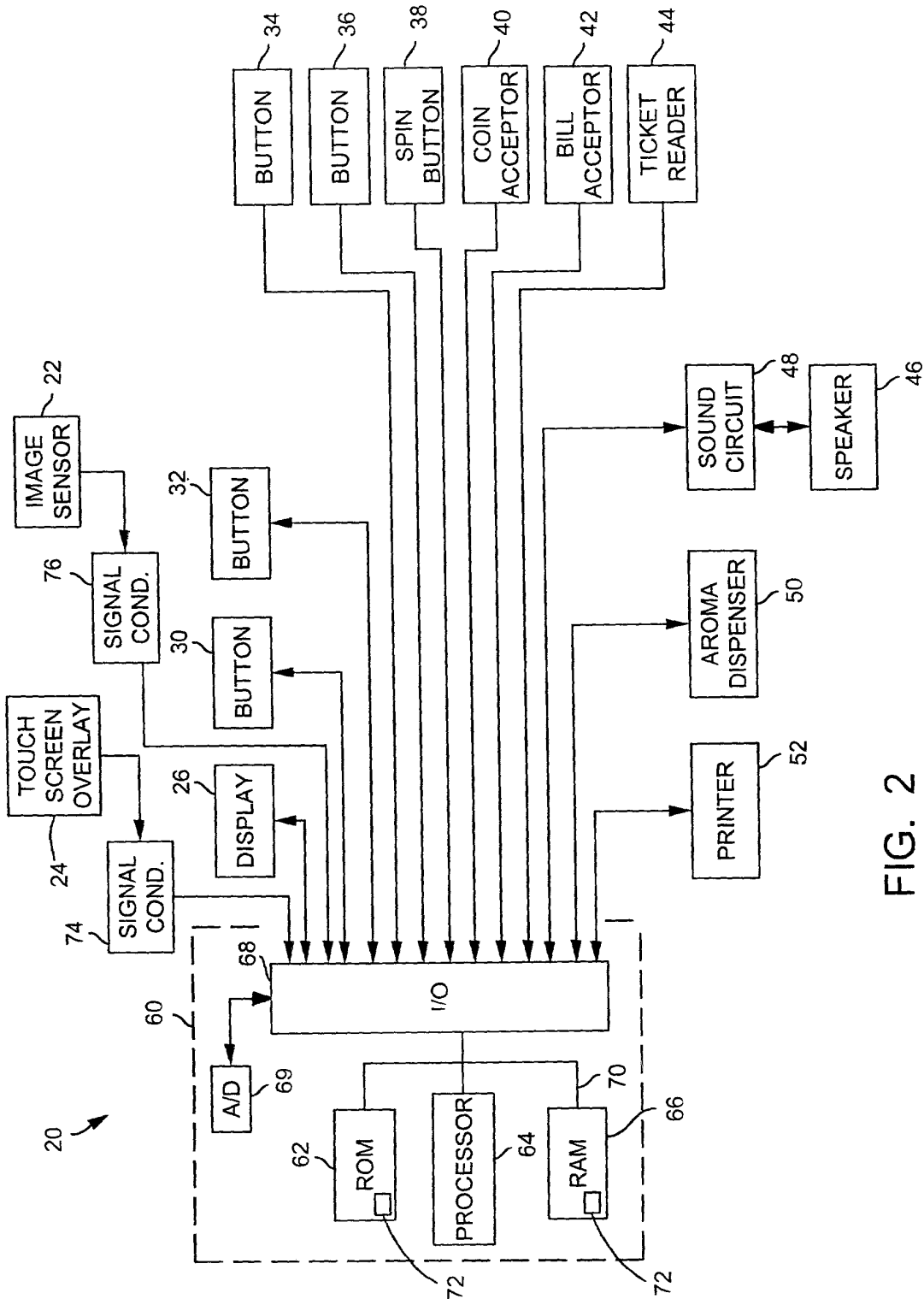
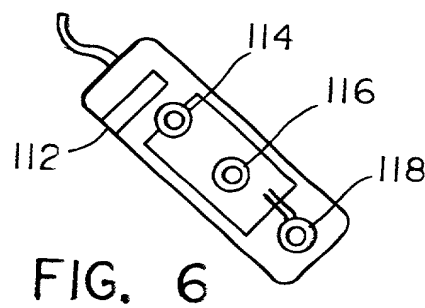
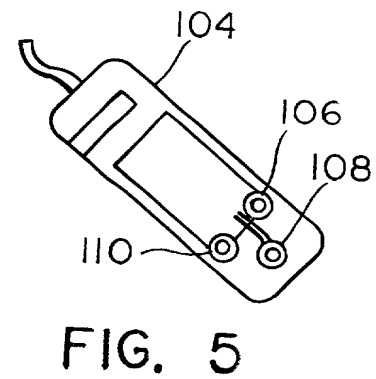
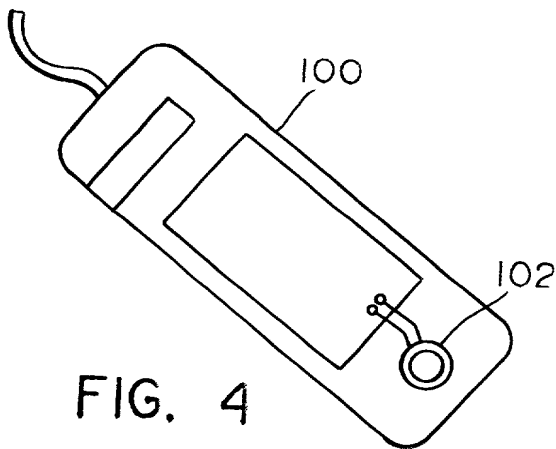
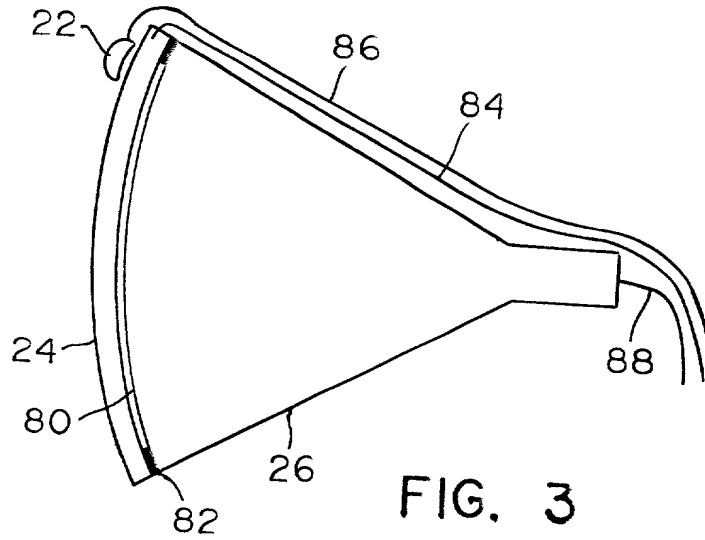


FIG. 2



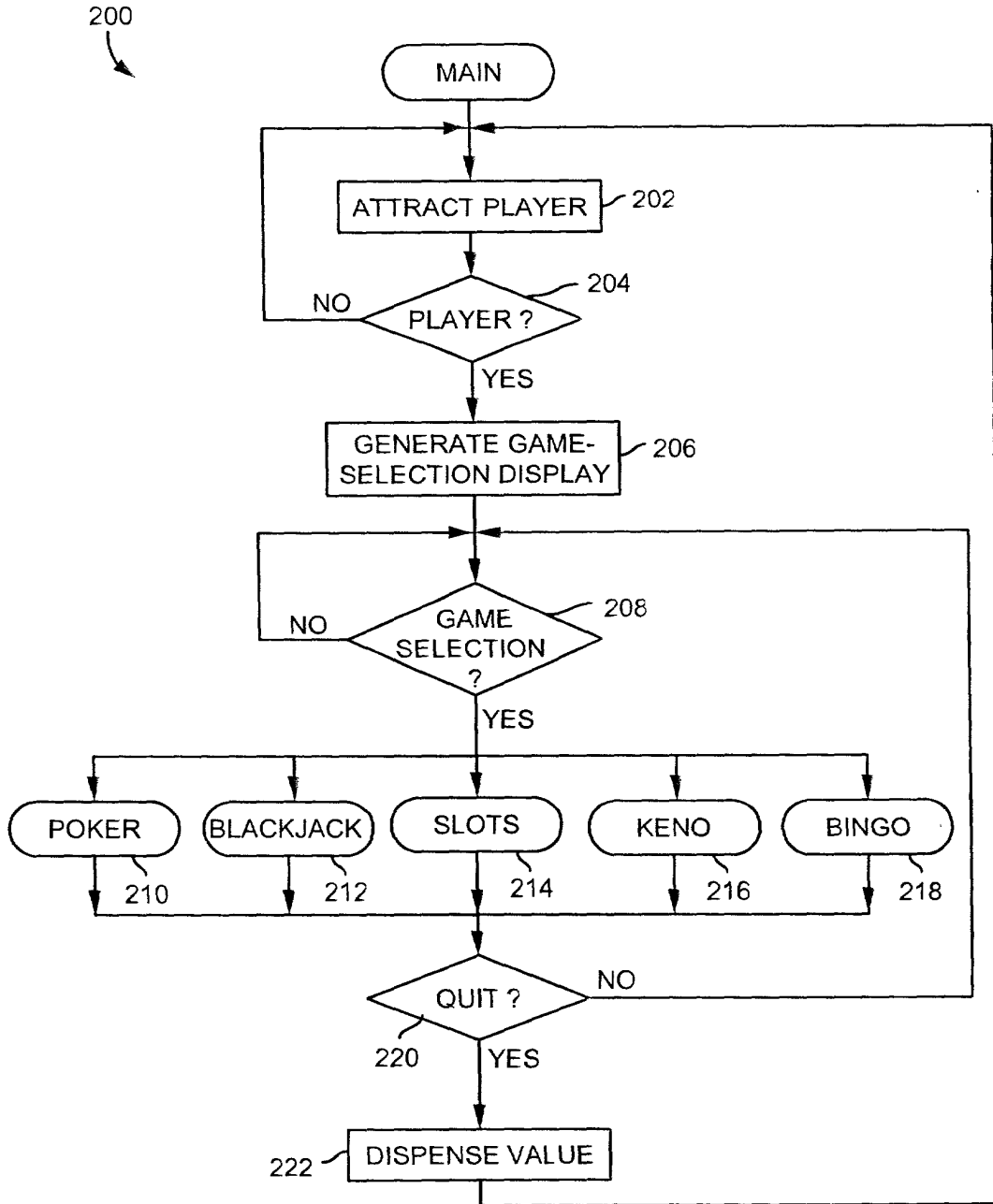


FIG. 7

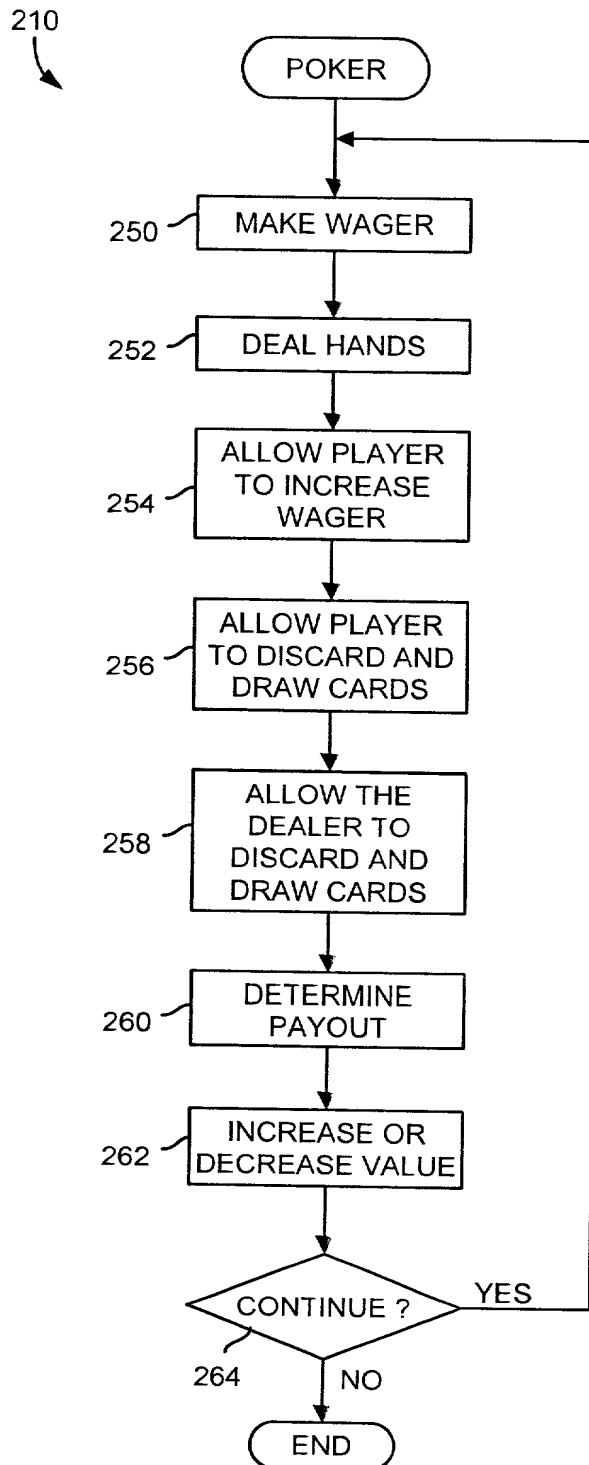


FIG. 8

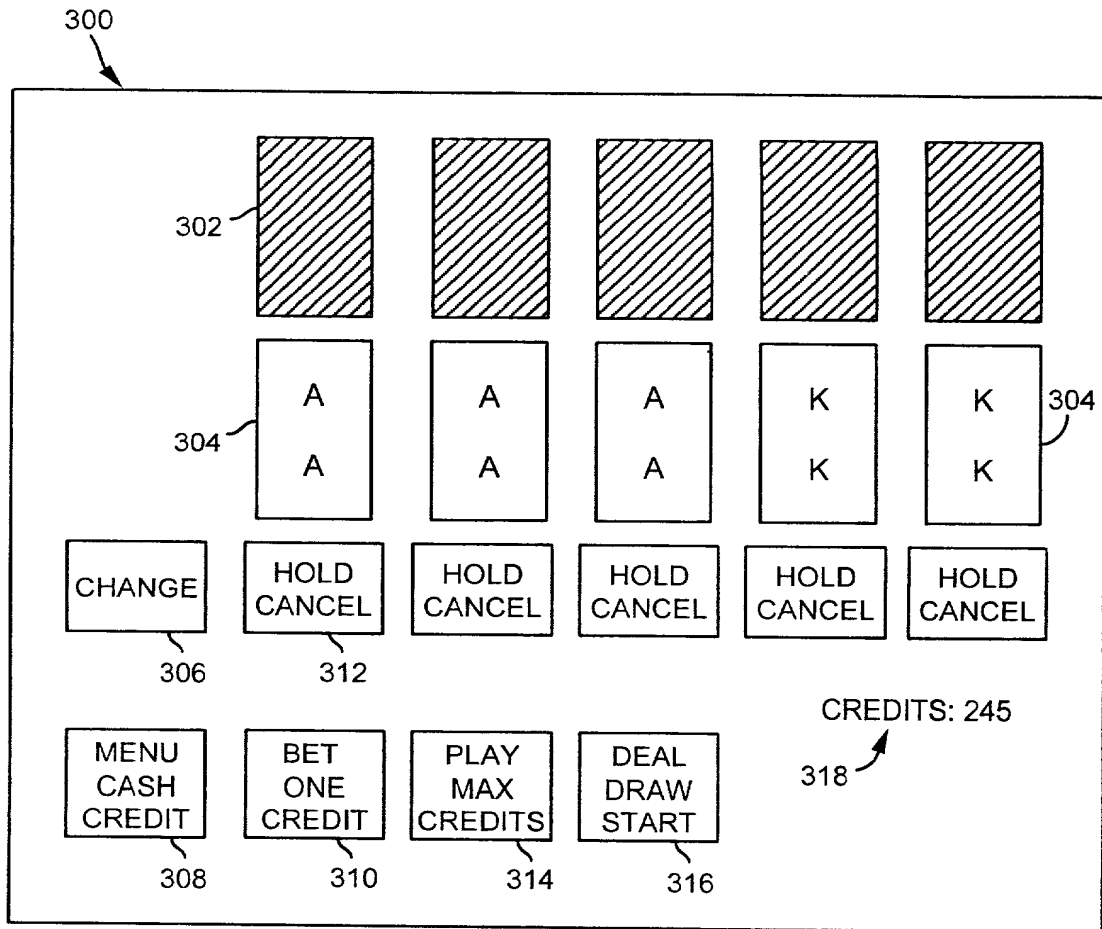


FIG. 9

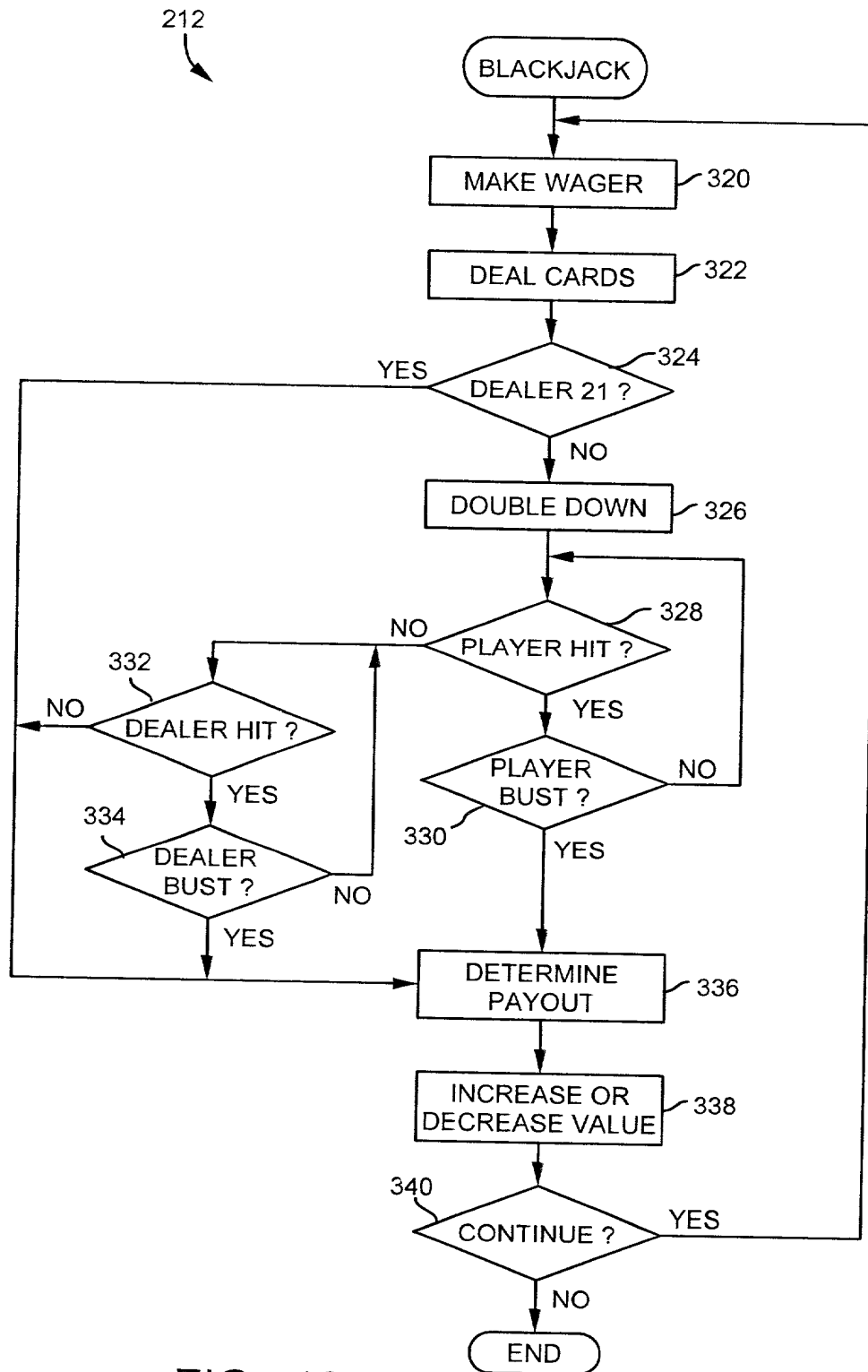


FIG. 10

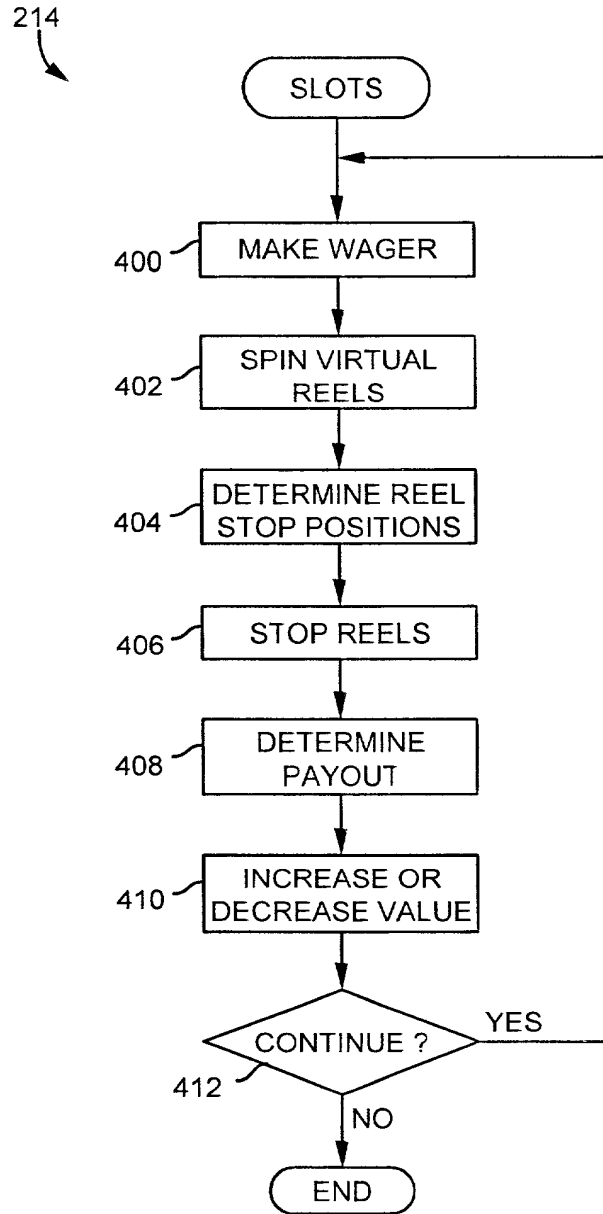


FIG. 11



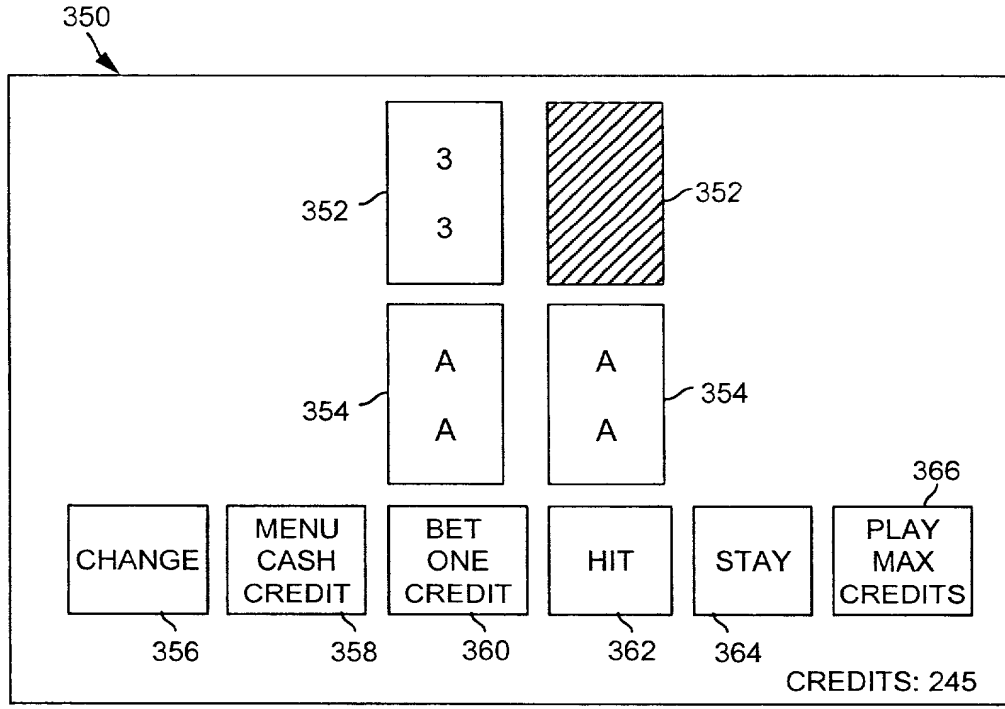


FIG. 12

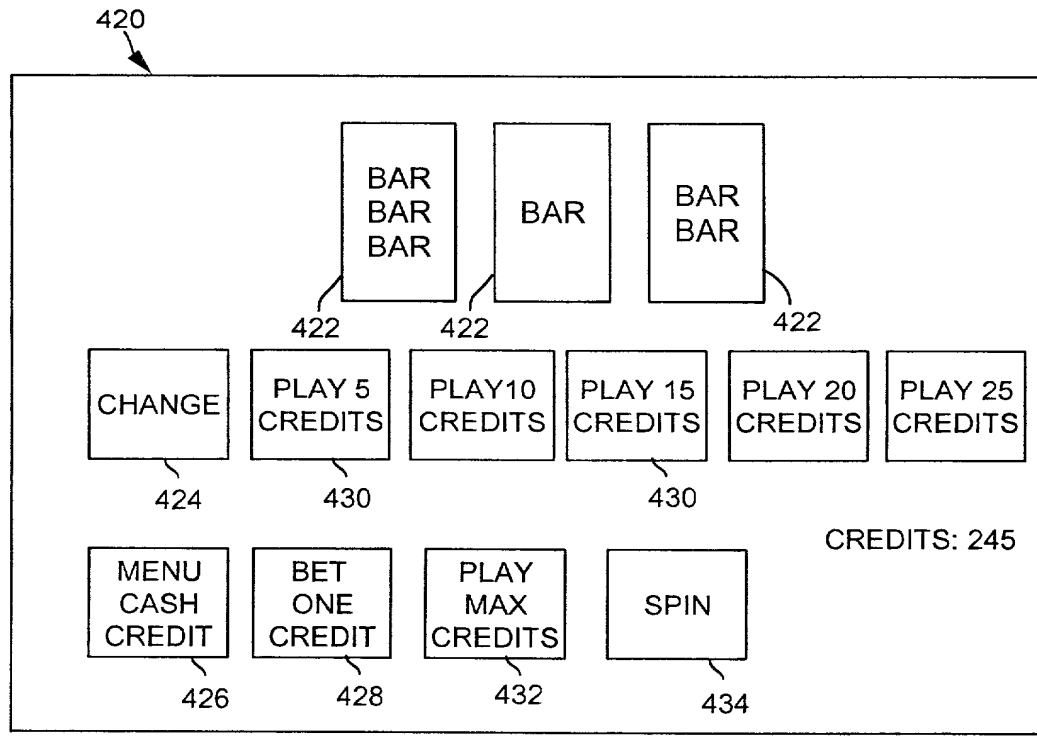


FIG. 13

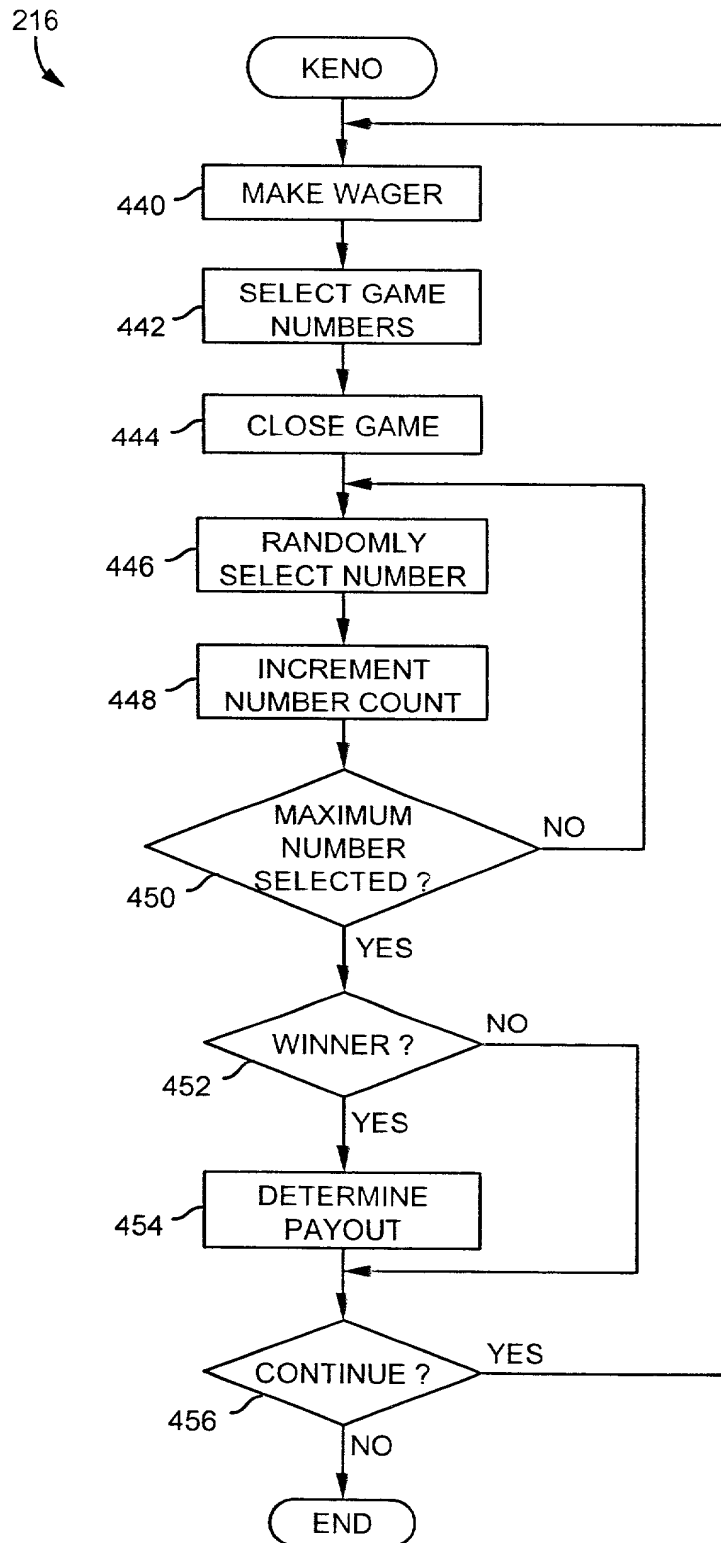


FIG. 14

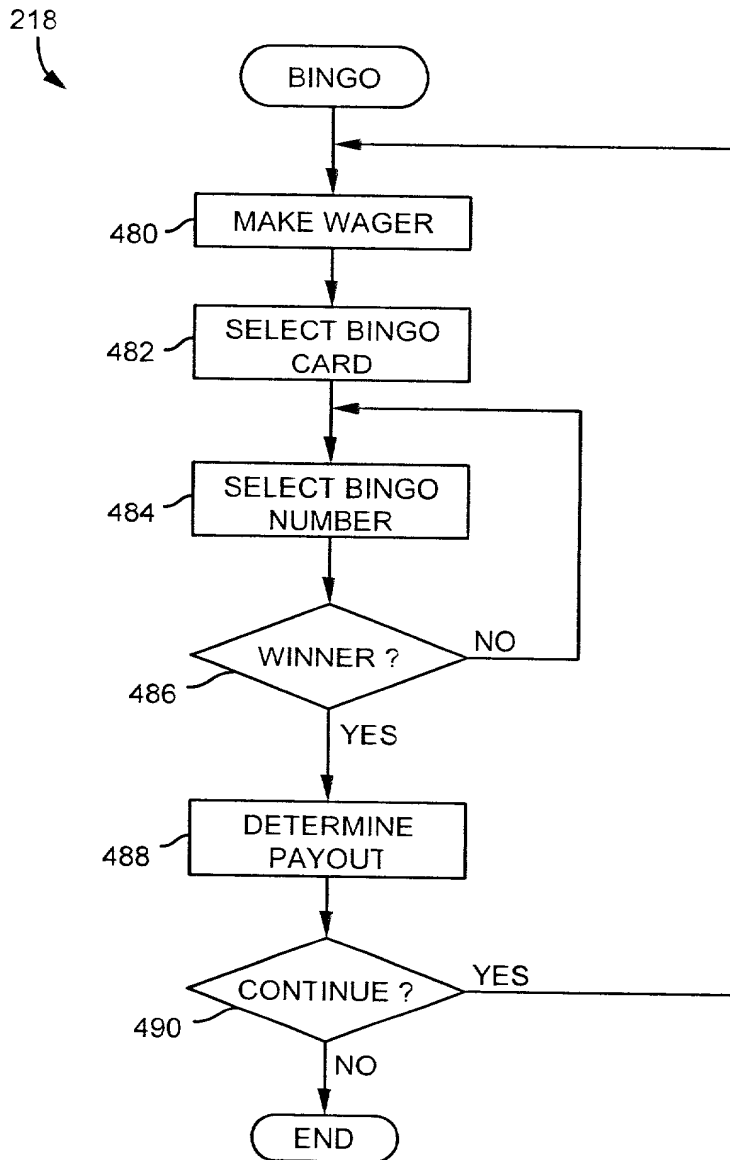


FIG. 15

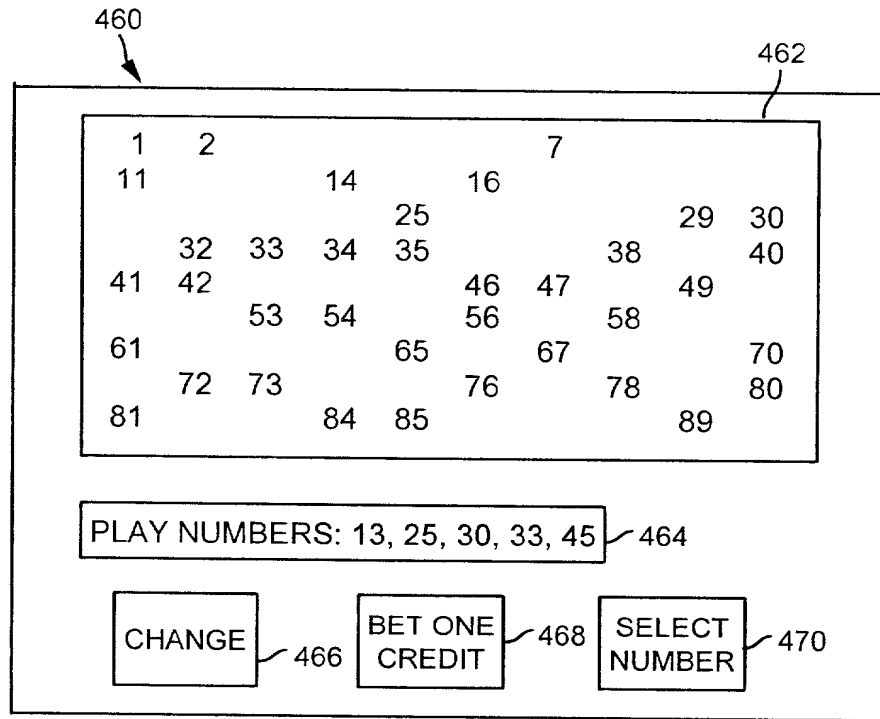


FIG. 16

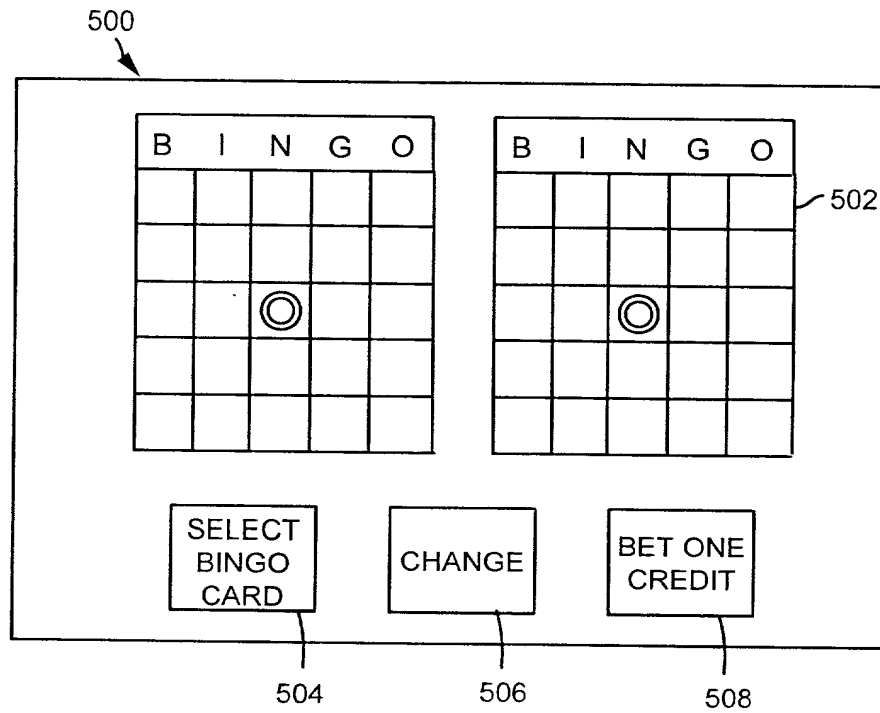


FIG. 17

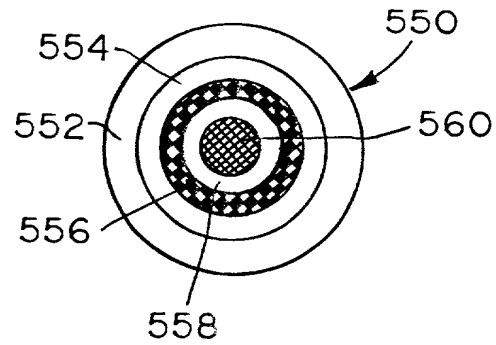


FIG. 18

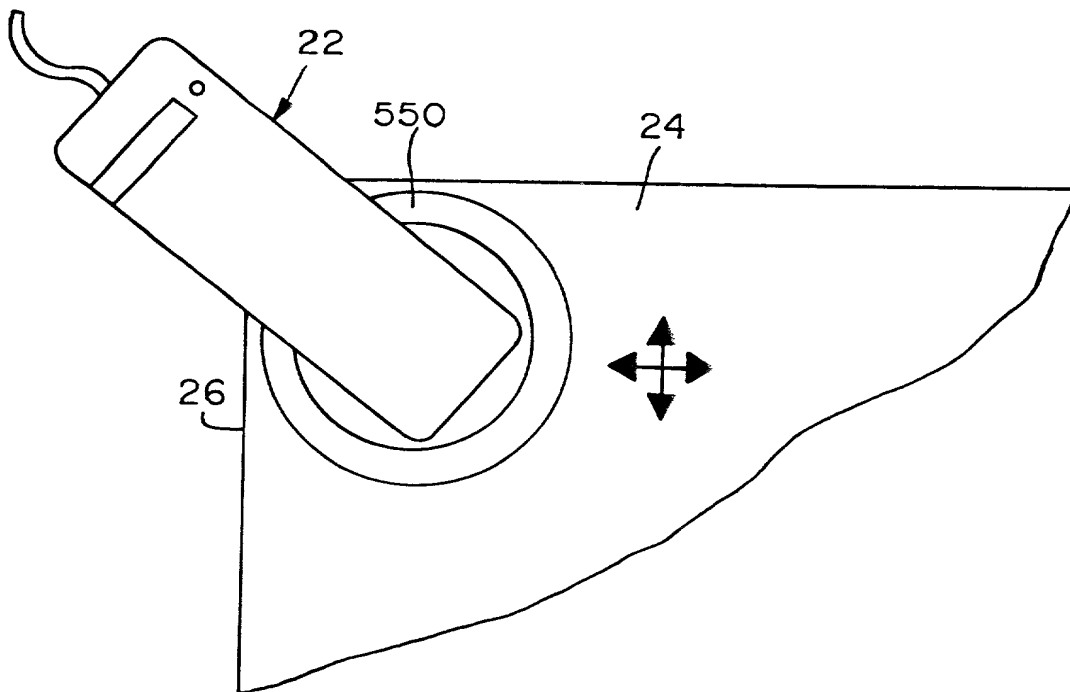


FIG. 19

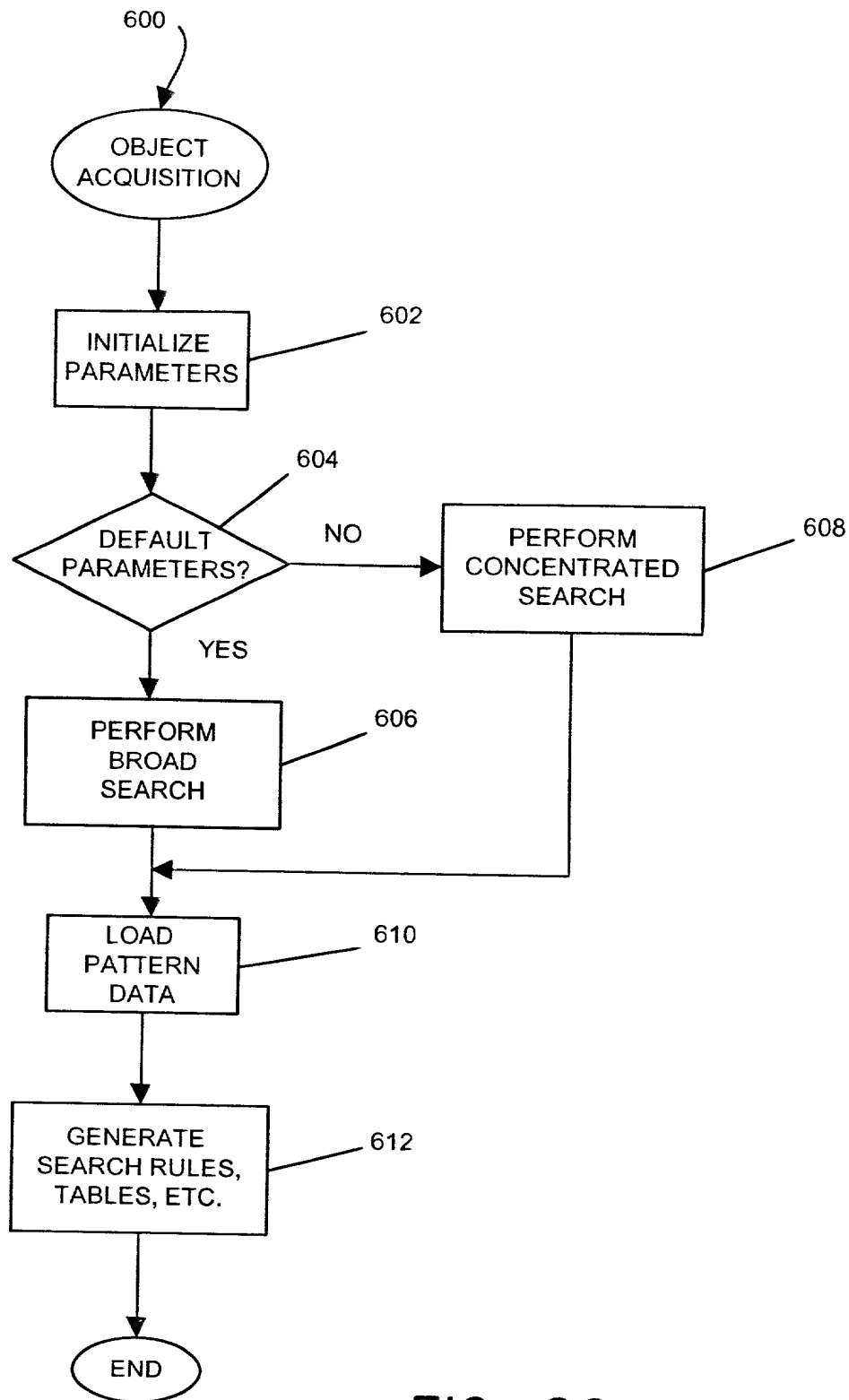


FIG. 20

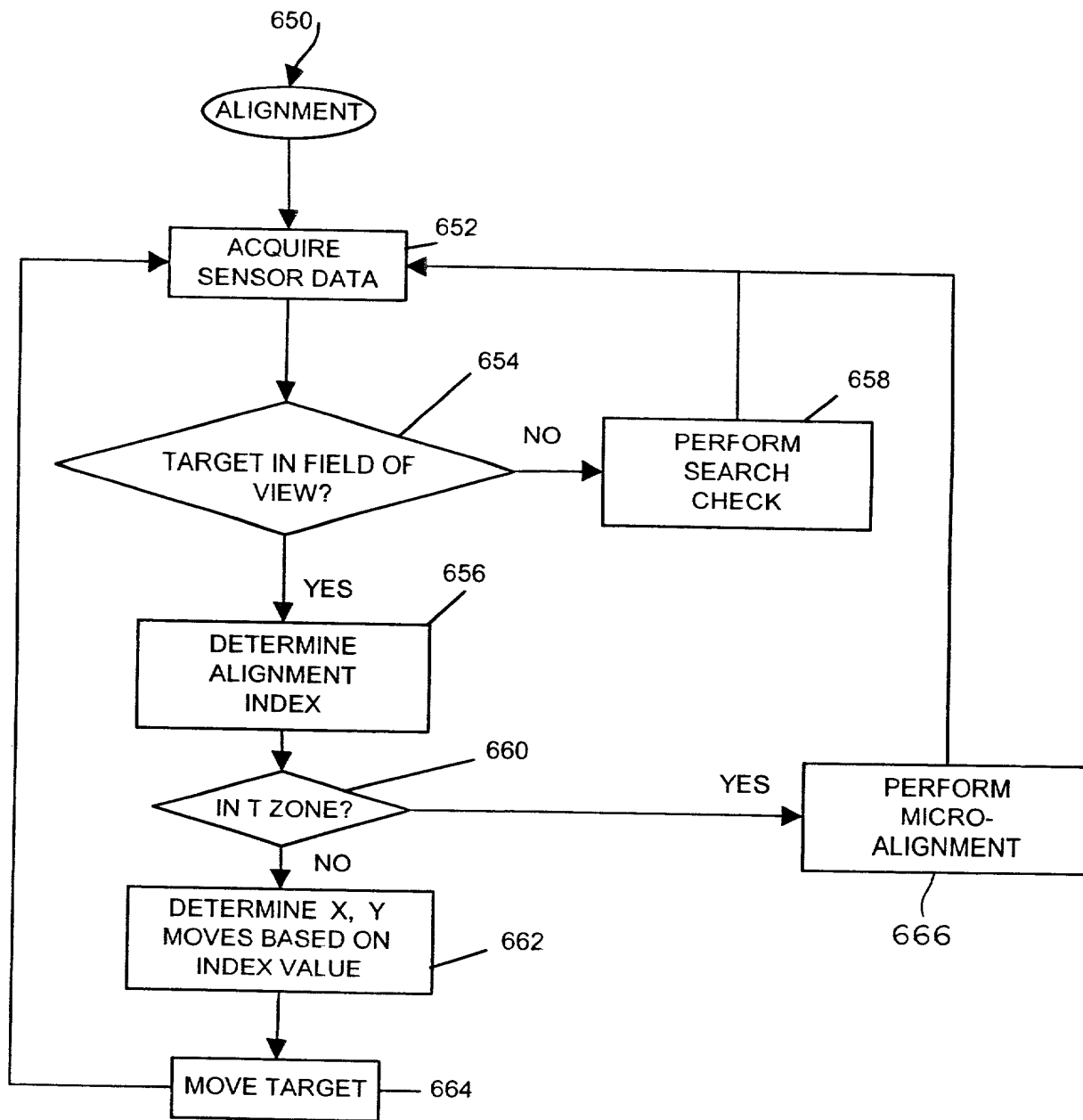


FIG. 21

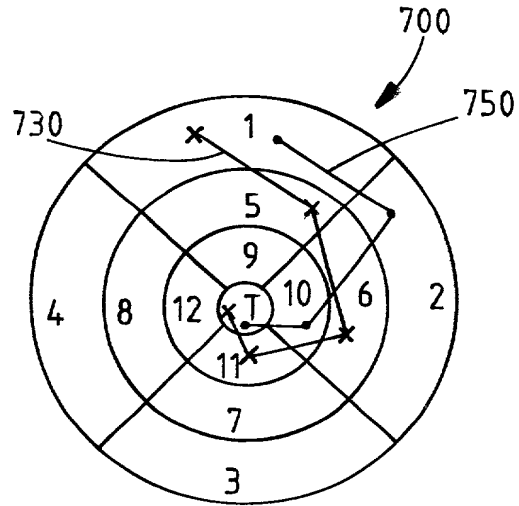


FIG. 22

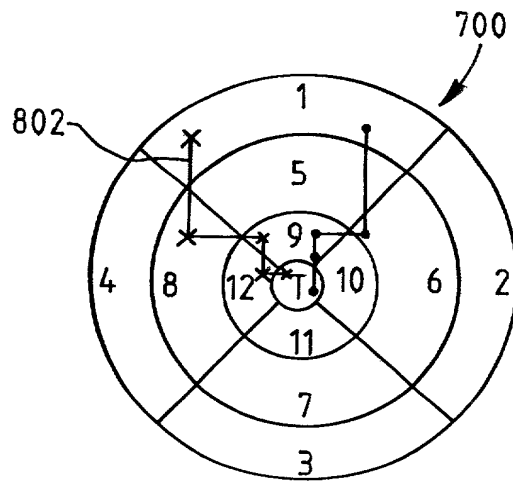


FIG. 24



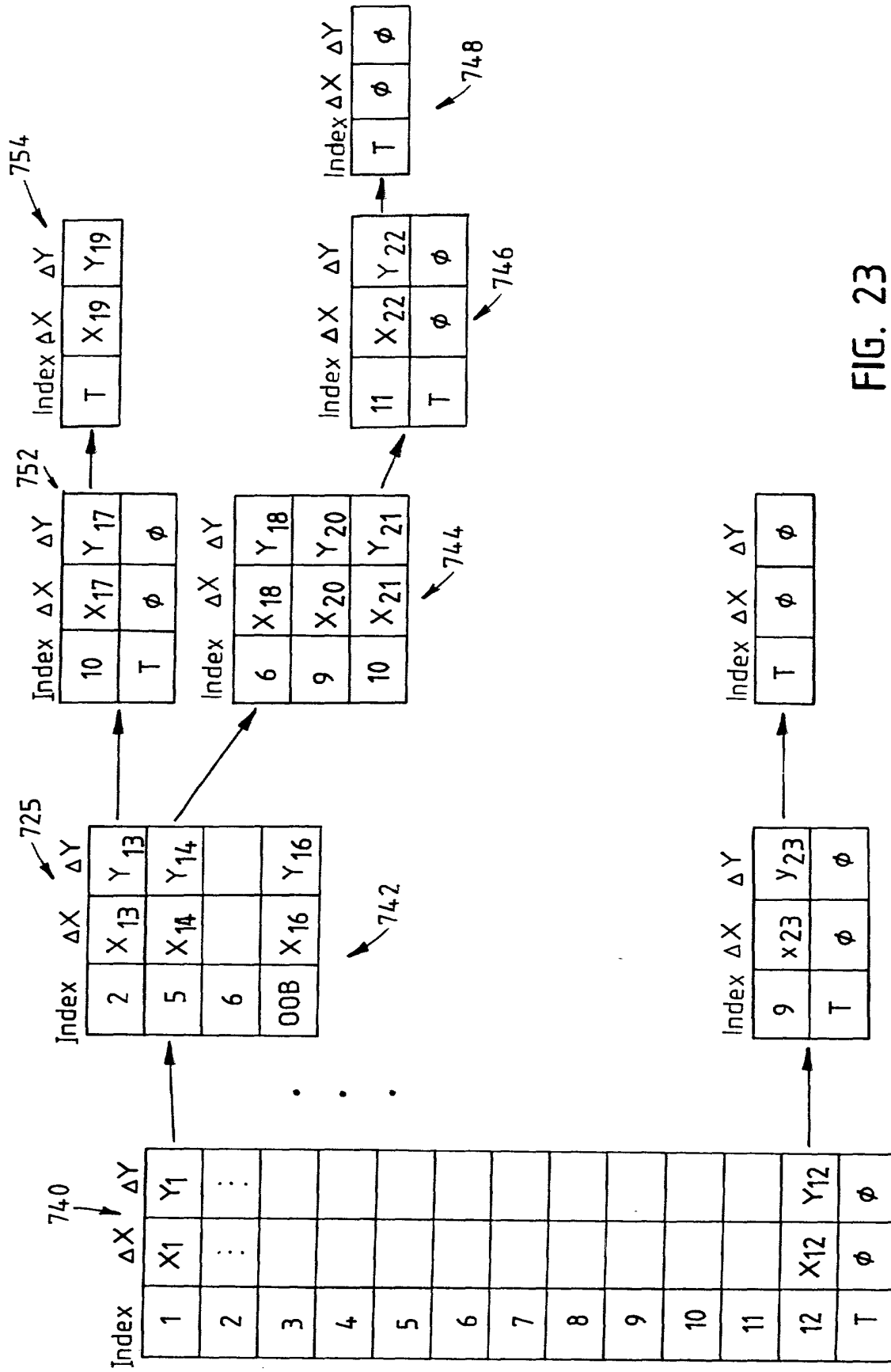


FIG. 23

800

(I)

	$\Delta X$	$\Delta Y$
1	$\phi$	$-Y_1$
2	$-X_1$	$\phi$
3	$\phi$	$Y_1$
4	$X_1$	$\phi$
5	$\phi$	$-K_1 Y_1$
6	$-K_1 X_1$	$\phi$
7	$\phi$	$K_1 Y_1$
8	$K_1 X_1$	$\phi$
9	$\phi$	$-K_2 Y_1$
10	$-K_2 X_1$	$\phi$
11	$\phi$	$K_2 Y_1$
12	$K_2 X_1$	$\phi$

Where:  $\phi \leq K_2 \leq K_1 \leq 1$   
& Where:  $X_1$  &  $Y_1$  may be dynamically adjusted

FIG. 25